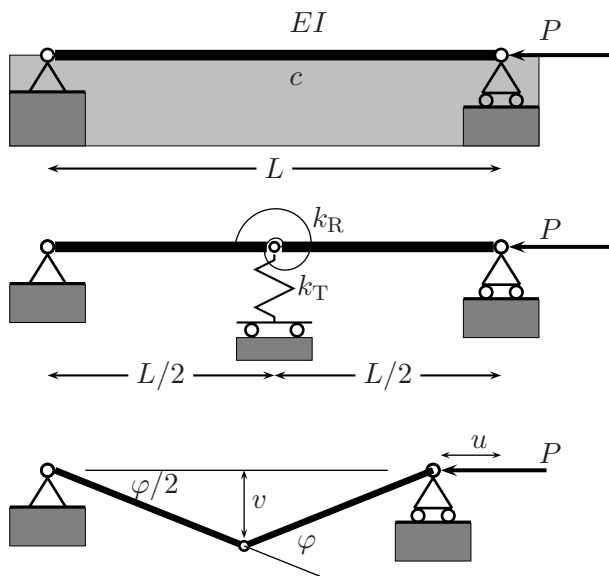


Stability of structures

1. exercise – equilibrium paths of simple structural models

Problem 1. Consider a beam on an elastic foundation. Idealize the beam as a discrete system of two equal length rigid bars connected by a linear rotational spring characterizing the bending rigidity of the beam. The foundation can be idealized with a linear translational spring. Determine all equilibrium paths and the critical load P_{cr} . The foundation coefficient is $c = \beta\pi^2 EI/L^4$, where β is a dimensionless constant. The spring constants are thus $k_T = \frac{1}{2}cL$ and $k_R = \frac{1}{4}\pi^2 EI/L$. Are the equilibrium paths near the critical point stable or unstable?



Solution. First, form the expressions for the horizontal displacement of the load point u and the vertical displacement of the joint:

$$u = 2 \cdot \frac{L}{2} (1 - \cos(\varphi/2)), \quad v = \frac{L}{2} \sin(\varphi/2).$$

The total potential energy is thus

$$\begin{aligned} \Pi &= \frac{1}{2}k_R\varphi^2 + \frac{1}{2}k_Tv^2 - Pu \\ &= \frac{1}{2}k_R\varphi^2 + \frac{1}{2}k_T\frac{L^2}{4}\sin^2(\varphi/2) - PL(1 - \cos(\varphi/2)) \\ &= \frac{1}{8}\pi^2\frac{EI}{L}\varphi^2 + \frac{1}{16}\beta\pi^2\frac{EI}{L}\sin^2(\varphi/2) - PL(1 - \cos(\varphi/2)). \end{aligned} \quad (1)$$

It is often advisable to make the expressions dimensionless, therefore let us denote

$$P = \lambda\frac{\pi^2 EI}{L^2}, \quad \tilde{\Pi} = \frac{L}{\pi^2 EI}\Pi,$$

which results in

$$\tilde{\Pi} = \frac{1}{8}\varphi^2 + \frac{1}{16}\beta\sin^2(\varphi/2) - \lambda(1 - \cos(\varphi/2)). \quad (2)$$

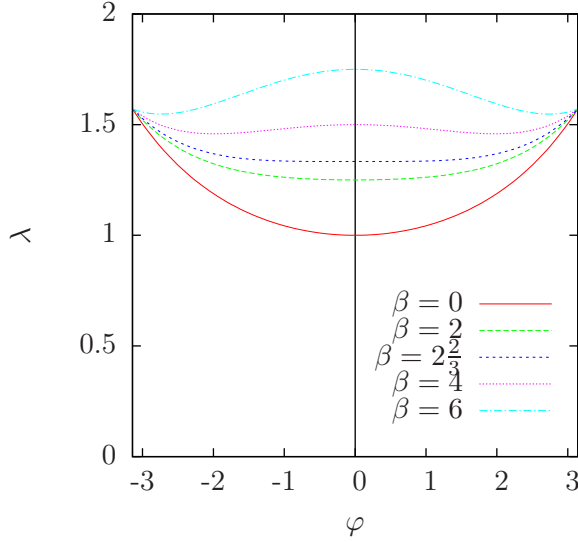


Figure 1: Equilibrium paths.

Equilibrium equation is

$$\frac{d\tilde{\Pi}}{d\varphi} = \frac{1}{4}\varphi + \frac{1}{16}\beta \sin(\varphi/2) \cos(\varphi/2) - \frac{1}{2}\lambda \sin(\varphi/2) = 0. \quad (3)$$

It is immediately noticed that $\varphi = 0$ is a solution for all values of the load parameter λ , the second solution is

$$\lambda = \frac{\varphi/2}{\sin(\varphi/2)} + \frac{1}{8}\beta \cos(\varphi/2). \quad (4)$$

These two equilibrium paths intersect at $\varphi = 0$, $\lambda = 1 + \frac{1}{8}\beta$, which is the bifurcation point. The critical load is then

$$P_{cr} = (1 + \frac{1}{8}\beta) \frac{\pi^2 EI}{L^2}.$$

Equilibrium paths with different β -values are shown in Fig. 1. For the stability investigation of these paths, we need the second derivative of the potential

$$\begin{aligned} \frac{d^2\tilde{\Pi}}{d\varphi^2} &= \frac{d}{d\varphi} \left(\frac{1}{4}\varphi + \frac{1}{16}\beta \sin(\varphi/2) \cos(\varphi/2) - \frac{1}{2}\lambda \sin(\varphi/2) \right) \\ &= \frac{1}{4} + \frac{1}{32}\beta \cos \varphi - \frac{1}{4}\lambda \cos(\varphi/2) \end{aligned} \quad (5)$$

Path I. On the primary path \mathcal{P}_I when $\varphi = 0$, thus

$$\left. \frac{d^2\tilde{\Pi}}{d\varphi^2} \right|_{\mathcal{P}_I} = \frac{1}{4} + \frac{1}{32}\beta - \frac{1}{4}\lambda. \quad (6)$$

Thus

$$\left. \frac{d^2\tilde{\Pi}}{d\varphi^2} \right|_{\mathcal{P}_I} > 0, \quad \text{when } \lambda < 1 + \frac{1}{8}\beta, \quad (7)$$

$$\left. \frac{d^2\tilde{\Pi}}{d\varphi^2} \right|_{\mathcal{P}_I} = 0, \quad \text{when } \lambda = 1 + \frac{1}{8}\beta, \quad (8)$$

$$\left. \frac{d^2\tilde{\Pi}}{d\varphi^2} \right|_{\mathcal{P}_I} < 0, \quad \text{when } \lambda > 1 + \frac{1}{8}\beta, \quad (9)$$

and we can conclude that

$$\mathcal{P}_I \text{ is } \begin{cases} \text{stable when} & \lambda < 1 + \frac{1}{8}\beta, \\ \text{unstable when} & \lambda > 1 + \frac{1}{8}\beta. \end{cases} \quad (10)$$

Stability of the bifurcation point $\lambda = 1 + \frac{1}{8}\beta$ cannot be determined from the second derivative.

Path II. Definition to the secondary equilibrium path \mathcal{P}_{II} is given in (4) and substituting it into (5) gives

$$\left. \frac{d^2\tilde{\Pi}}{d\varphi^2} \right|_{\mathcal{P}_{II}} = \frac{1}{4} + \frac{1}{32}\beta \cos \varphi - \frac{1}{4} \left(\frac{\varphi/2}{\sin(\varphi/2)} + \frac{1}{8}\beta \cos(\varphi/2) \right) \cos(\varphi/2) \quad (11)$$

$$= \frac{1}{4} - \frac{\varphi/8}{\tan(\varphi/2)} + \frac{1}{32}\beta (\cos \varphi - \cos^2(\varphi/2)) \quad (12)$$

$$= \frac{1}{4} \left(1 - \frac{\varphi/2}{\tan(\varphi/2)} - \frac{1}{8}\beta \sin^2(\varphi/2) \right). \quad (13)$$

It can be seen that depending on the value of β , the secondary path \mathcal{P}_{II} can be either stable or unstable.

Let us investigate stability of the secondary path near the critical point $\varphi = 0$, $\lambda = 1 + \frac{1}{8}\beta$. Remember that

$$\begin{aligned} \sin x &= x - \frac{1}{3!}x^3 + \frac{1}{5!}x^5 - \dots, \\ \cos x &= 1 - \frac{1}{2!}x^2 + \frac{1}{4!}x^4 - \dots, \\ \tan x &= x + \frac{1}{3}x^3 + \frac{2}{15}x^5 + \dots, \\ \frac{1}{1+x} &= 1 - x + x^2 - x^3 + \dots. \end{aligned}$$

Series expansion of (5) is

$$\begin{aligned} \left. \frac{d^2\tilde{\Pi}}{d\varphi^2} \right|_{\mathcal{P}_{II}} &= \frac{1}{4} \left(1 - \frac{\varphi/2}{\varphi/2 + \frac{1}{3}(\varphi/2)^3} \right) - \frac{1}{32}\beta(\varphi/2)^2 \left(1 - \frac{1}{6}(\varphi/2)^2 \right) + \text{h.o.t.} \\ &= \frac{1}{4} \left(\frac{1}{3} - \frac{1}{8}\beta \right) (\varphi/2)^2 + \text{h.o.t.} \end{aligned} \quad (14)$$

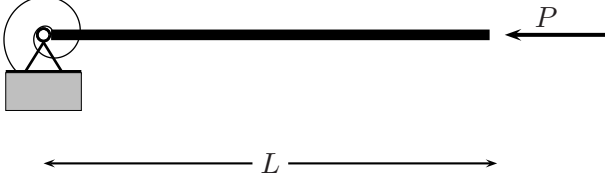
Thus, it can be concluded that when $|\varphi| \ll 1$ then \mathcal{P}_{II} is initially stable if $\beta < 8/3 = 2\frac{2}{3}$ and unstable if $\beta > 2\frac{2}{3}$.

Notice that increasing the foundation stiffness, i.e. increasing β , increases the critical bifurcation load, but it makes the secondary paths (also known as post-buckling paths) more unstable!

Problem 2. Determine all equilibrium paths of the simple rigid bar-spring system. Investigate stability of these paths. Determine also the possible critical points and the corresponding load values P_{cr} . The constitutive relation of the spring is

$$M = k_1\varphi + k_2\varphi^3, \quad k_1 > 0.$$

Investigate the effect of the nonlinear term k_2 , i.e. use different values of the ratio $\alpha = k_2/k_1$.



Solution. The total potential energy is

$$\begin{aligned} \Pi &= \int_0^\varphi M d\varphi - PL(1 - \cos \varphi) \\ &= \frac{1}{2}k_1\varphi^2 + \frac{1}{4}k_2\varphi^4 - PL(1 - \cos \varphi). \end{aligned} \quad (15)$$

Equilibrium equation is

$$\frac{d\Pi}{d\varphi} = k_1\varphi(1 + \alpha\varphi^2) - PL \sin \varphi = 0. \quad (16)$$

Immediately we notice that $\varphi = 0$ is a solution. Defining dimensionless load parameter as $P = \lambda k_1/L$, i.e. $\lambda = PL/k_1$, we have for the secondary path

$$\lambda = \frac{\varphi(1 + \alpha\varphi^2)}{\sin \varphi}. \quad (17)$$

The primary- and secondary paths intersect at $\varphi = 0$, $\lambda = 1$, which is the critical bifurcation point.

Let us investigate stability of the paths.

$$\tilde{\Pi} = \Pi/k_1 = \frac{1}{2}\varphi^2 + \frac{1}{4}\alpha\varphi^4 - \lambda(1 - \cos \varphi), \quad (18)$$

$$\frac{d\tilde{\Pi}}{d\varphi} = \varphi + \alpha\varphi^3 - \lambda \sin \varphi = 0, \quad (19)$$

$$\frac{d^2\tilde{\Pi}}{d\varphi^2} = 1 + 3\alpha\varphi^2 - \lambda \cos \varphi. \quad (20)$$

Path I. Primary path \mathcal{P}_I : $\varphi = 0$, then

$$\left. \frac{d^2\tilde{\Pi}}{d\varphi^2} \right|_{\mathcal{P}_I} \begin{cases} > 0 & \text{when } \lambda < 1 & \text{stable} \\ = 0 & \text{when } \lambda = 1 & ? \\ < 0 & \text{when } \lambda > 1 & \text{unstable} \end{cases} \quad (21)$$

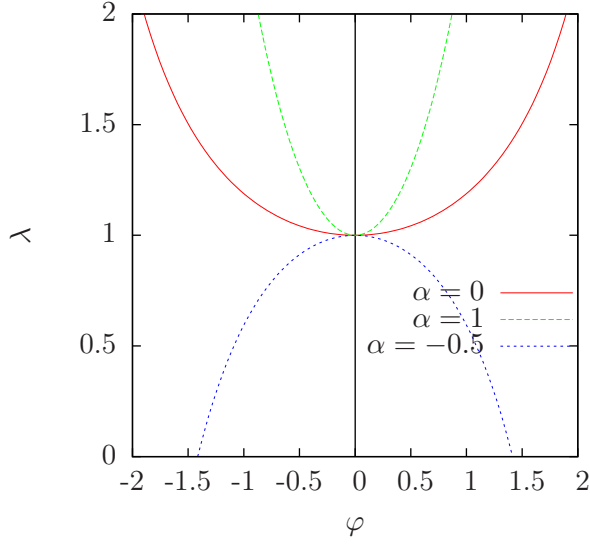


Figure 2: Equilibrium paths with different values of α .

Path II. Secondary path \mathcal{P}_{II} defined in (17), then on \mathcal{P}_{II}

$$\begin{aligned}
 \left. \frac{d^2\tilde{\Pi}}{d\varphi^2} \right|_{\mathcal{P}_{II}} &= 1 + 3\alpha\varphi^2 - \frac{\varphi}{\tan\varphi} - \alpha\frac{\varphi^3}{\tan\varphi} \\
 &= 1 + 3\alpha\varphi^2 - \left(1 - \frac{1}{3}\varphi^2\right) - \alpha\varphi^2\left(1 - \frac{1}{3}\varphi^2\right) + \text{h.o.t.} \\
 &= \left(\frac{1}{3} + 2\alpha\right)\varphi^2 + \text{h.o.t.}
 \end{aligned} \tag{22}$$

Secondary path \mathcal{P}_{II} is thus stable if $\frac{1}{3} + 2\alpha > 0$.